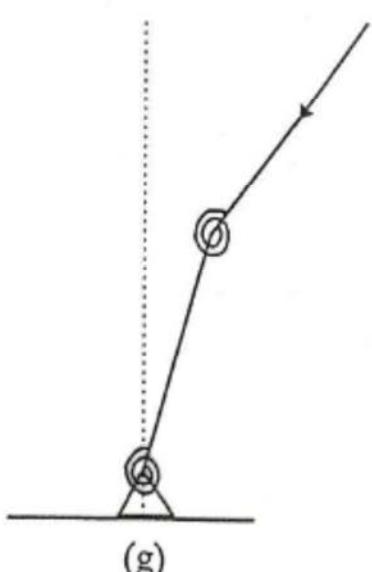
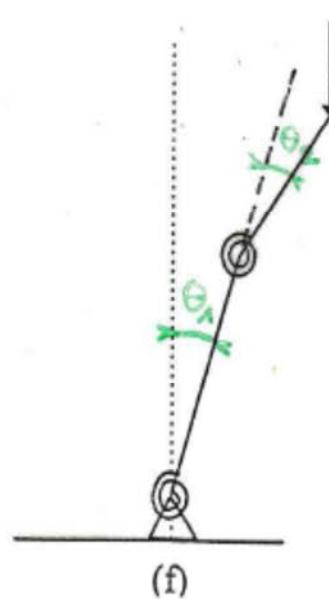
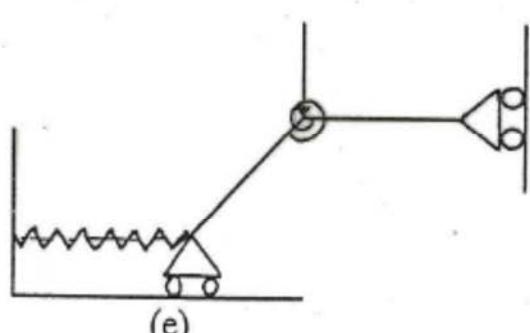
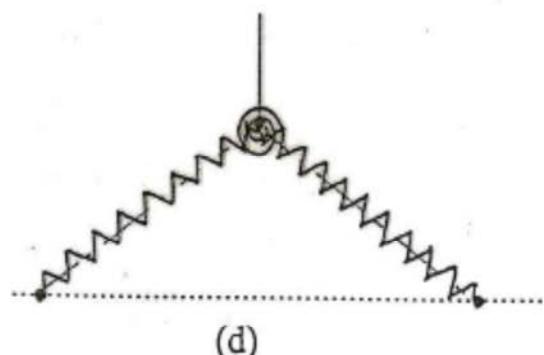
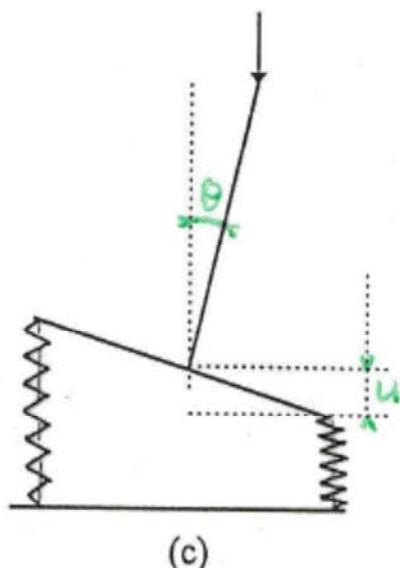
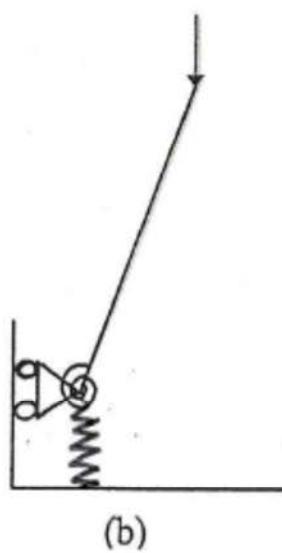
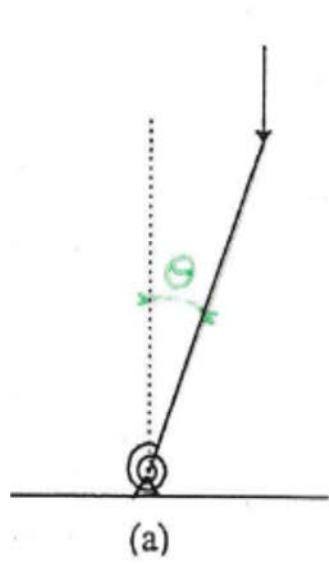
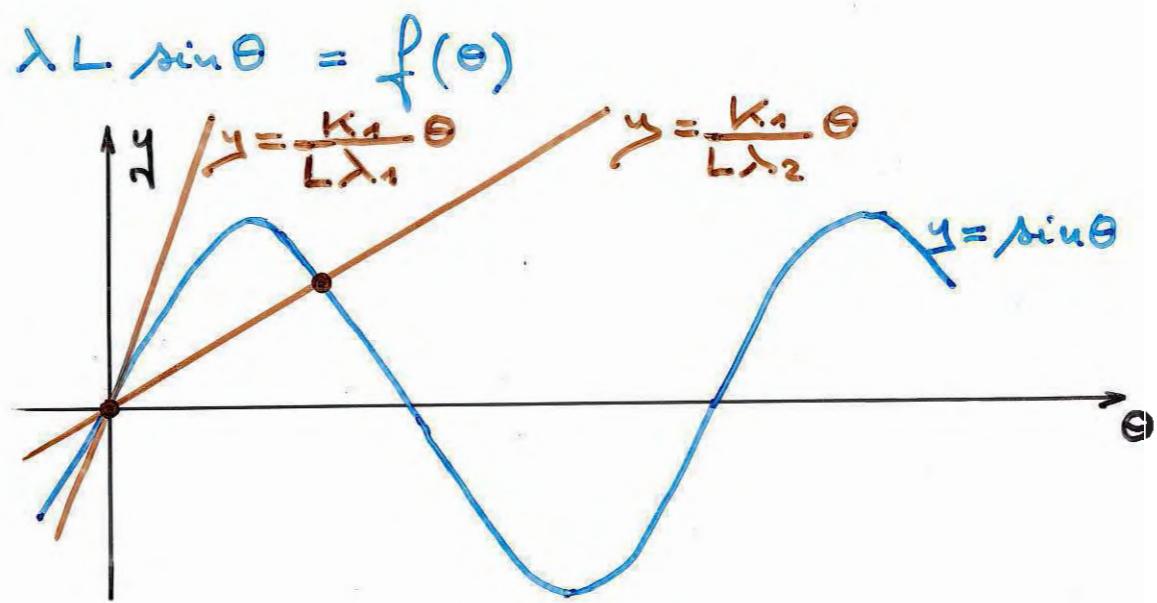
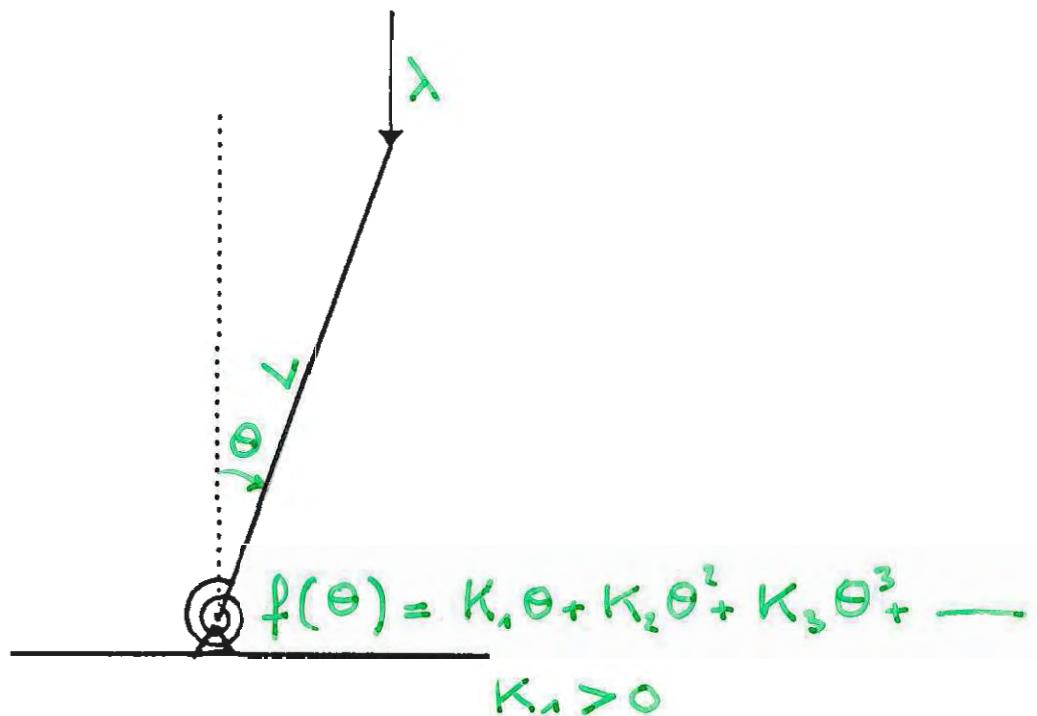
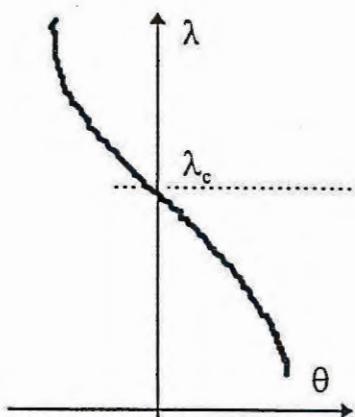


SIMPLE MODELS AND STRUCTURES

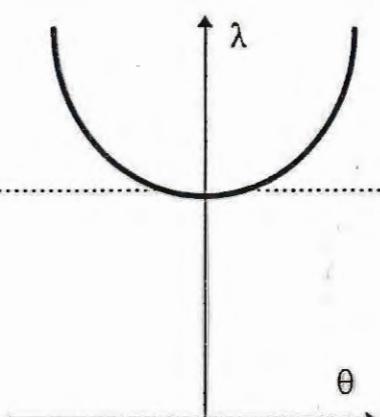




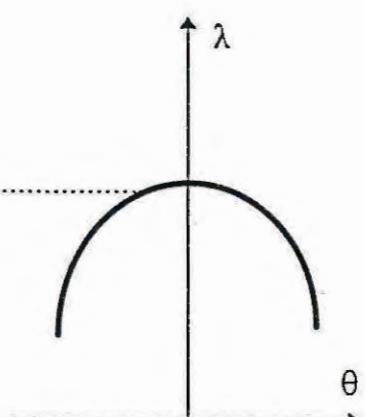
$$\left\{ \begin{array}{l} \theta = 0, \quad \forall \lambda \in \mathbb{R}^+ \\ \lambda = \frac{f(\theta)}{L \sin \theta} \end{array} \right.$$



(a) $K_2 < 0$



(b) $K_2 = 0, \lambda_1 = 0, \lambda_2 > 0$

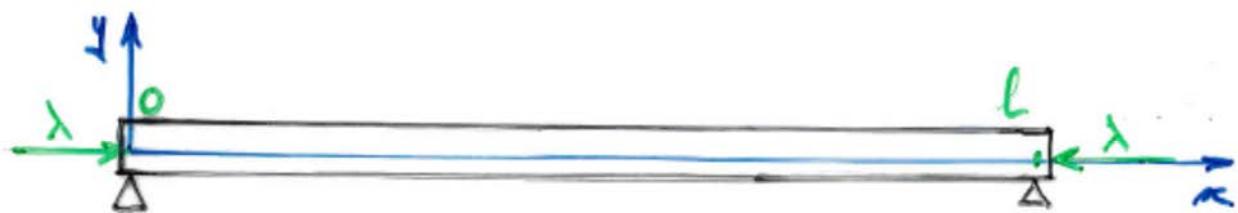


(c) $K_2 = 0, \lambda_1 = 0, \lambda_2 < 0$

$$\lambda = \lambda_c + \lambda_1 \theta + \lambda_2 \theta^2 + \dots$$

$$\left\{ \begin{array}{l} \lambda_c = \frac{K_1}{L} \\ \lambda_1 = \lambda_c \frac{K_2}{K_1} \\ \lambda_2 = \lambda_c \left[\frac{K_2}{K_1} + \frac{1}{6} \right] \\ \vdots \end{array} \right.$$

THE COMPRESSED BEAM



Kinematics :

$$\begin{cases} \varepsilon(x) = u' + \frac{(v')^2}{2}, & (\cdot)' \equiv \frac{d}{dx} \\ \kappa(x) = -v'' \end{cases}$$

$$\hookrightarrow \delta(x, y) = u'(x) + \frac{(v'(x))^2}{2} - y v''(x)$$

Equilibrium :

$$\begin{cases} N' = 0 \\ M'' + N s\kappa = 0 \end{cases}$$

Constitutive law :

$$\begin{cases} N = E S \left(u' + \frac{(v')^2}{2} \right) \\ M = E I v'' \end{cases}$$

\hookrightarrow

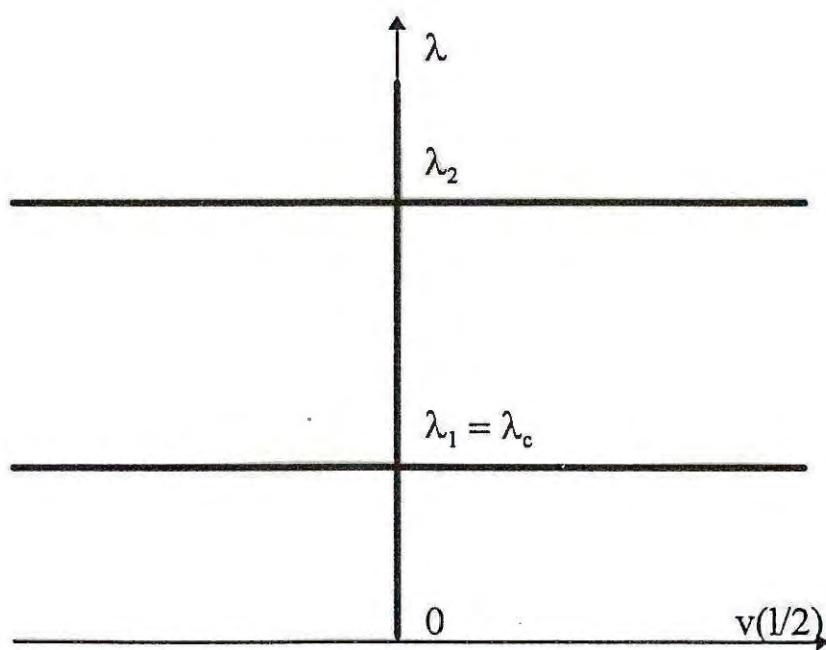
$$\begin{aligned} N &= C^{\text{ext}} = -\lambda \\ (E I v'')'' + \lambda v'' &= 0 \\ + \text{B.C.} \end{aligned}$$

- * Uniform cross-section
- * S. S. Boundary Conditions

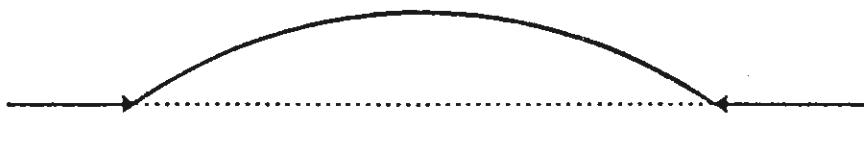
$$\begin{cases} EI v'' + \lambda v = 0 \\ v(0) = v(l) = 0 \end{cases}$$

$$\Rightarrow \lambda_n = \frac{n^2 \pi^2 EI}{l^2}$$

↳ Bifurcation diagram:

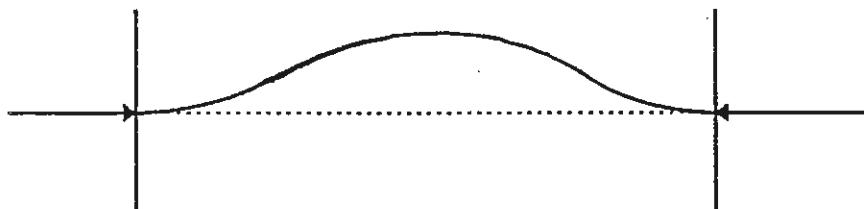


- Extrémités simplement appuyées:



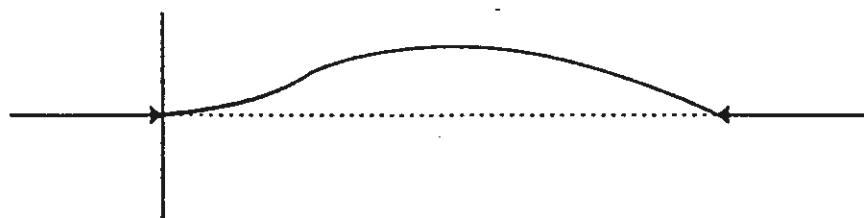
$$\lambda_c = \frac{\pi^2 EI}{\ell^2}$$

- Extrémités encastrées:



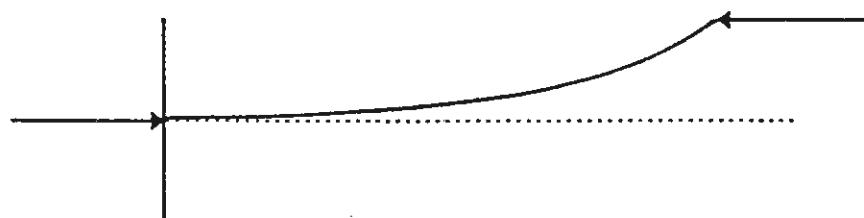
$$\lambda_c = \frac{4\pi^2 EI}{\ell^2}$$

- Appui simple à une extrémité, encastrement à l'autre:

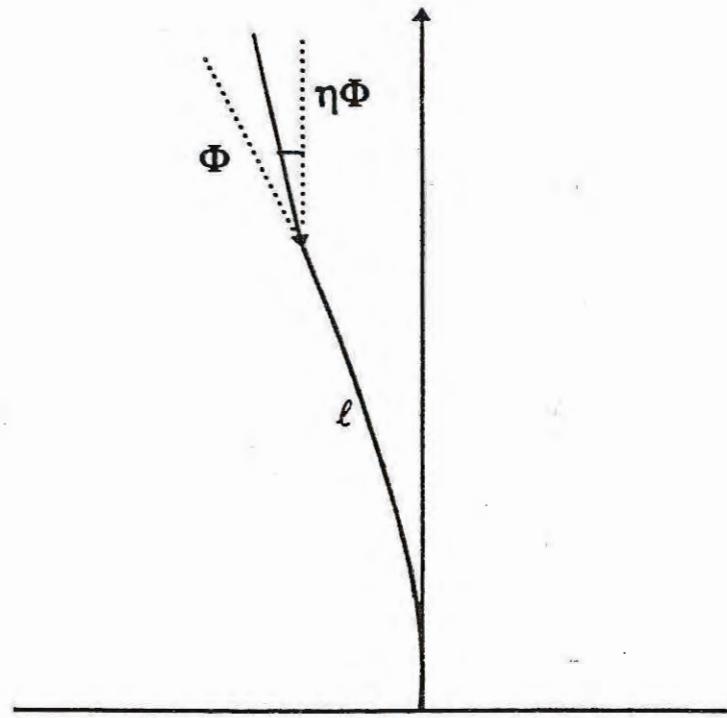


$$\lambda_c = 2.04 \frac{\pi^2 EI}{\ell^2}$$

- Une extrémité encastrée, l'autre libre:



$$\lambda_c = \frac{\pi^2 EI}{4\ell^2}$$



$$EI v_{\text{trans}} + \lambda v_{\text{rot}} + m v_{\text{tot}} = 0$$

$$v(n,t) = e^{i\omega n} f(n) \Rightarrow \begin{cases} EI f^{(4)} + \lambda f'' - m\omega^2 f = 0 \\ f(0) = f'(0) = f''(L) = 0 \\ f'''(L) - (\eta - 1) \frac{\lambda}{EI} f'(L) = 0 \end{cases}$$

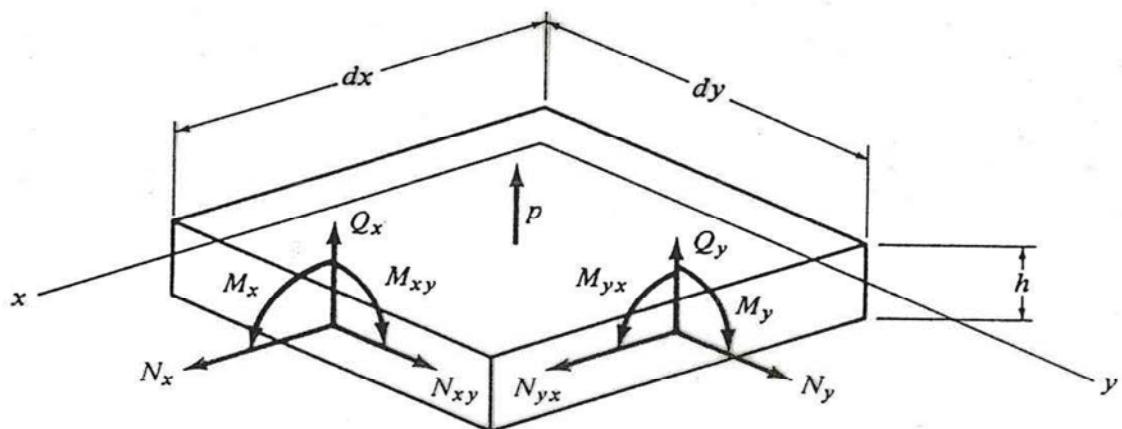
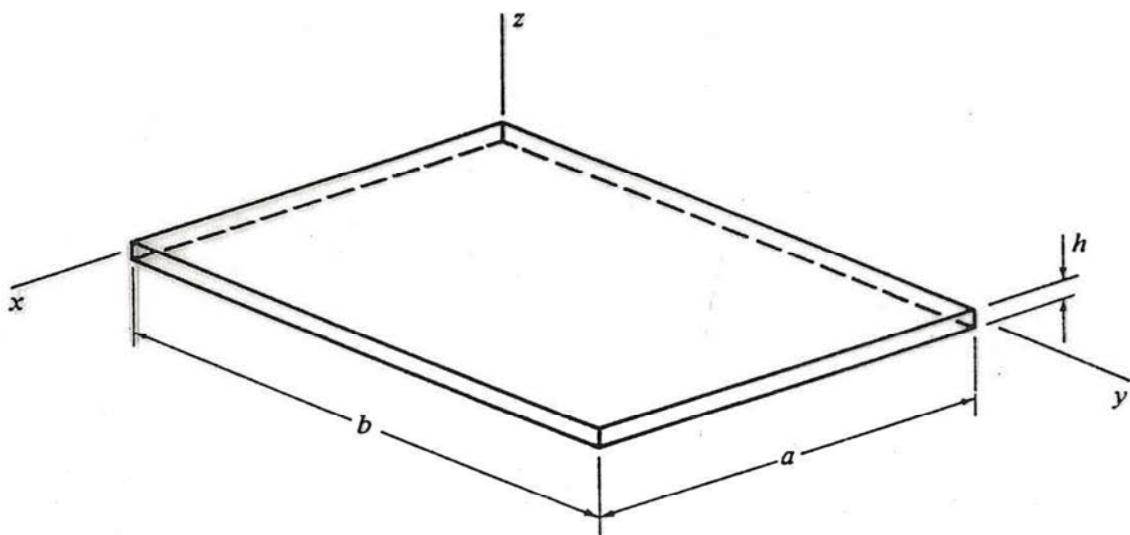
1/ $\omega = 0$:

$$\boxed{\lambda_c = \frac{\pi^2 EI}{L^2} \quad \frac{1}{\pi^2} \left[\arccos \frac{\eta}{\eta - 1} \right]^2}$$

$\Rightarrow \eta \leq 0.5!$

$$2/ \underline{\eta > 0.5} \Rightarrow \omega^2 = 1.24 \frac{\pi^2 EI}{m L^4} \quad \text{à} \quad \lambda = 20.05 \frac{EI}{L^2}$$

THE VON KARMAN PLATE



Kirchhoff - Love kinematics:

$$\left\{ \begin{array}{l} \bar{u} = u + \beta_x \beta_x \\ \bar{v} = v + \beta_y \beta_y \\ \bar{w} = w \end{array} \right. \quad \text{where} \quad \left\{ \begin{array}{l} \beta_x = -w_{,xx} \\ \beta_y = -w_{,yy} \end{array} \right.$$

u, v, w : defns of (x, y) only.

* Small strains, finite displacements

$$\left\{ \begin{array}{l} \xi_x = u_{,xx} + \frac{1}{2}(w_{,x})^2 \\ \xi_y = v_{,yy} + \frac{1}{2}(w_{,y})^2 \\ \gamma_{xy} = u_{,yy} + v_{,xx} + w_{,x}w_{,y} \end{array} \right. \quad \left\{ \begin{array}{l} k_x = -w_{,xxx} \\ k_y = -w_{,yyy} \\ k_{xy} = -w_{,xyy} \end{array} \right.$$

* Constitutive law:

$$\left\{ \begin{array}{l} N_x = C(\xi_x + \nu \xi_y) \\ N_y = C(\xi_y + \nu \xi_x) \\ N_{xy} = C \frac{1-\nu}{2} \gamma_{xy} \end{array} \right. \quad \left\{ \begin{array}{l} M_x = D(k_x + \nu k_y) \\ M_y = D(k_y + \nu k_x) \\ M_{xy} = D(1-\nu) k_{xy} \end{array} \right.$$

with:

$$C \equiv \frac{Eh}{1-\nu^2}, \quad D \equiv \frac{Eh^3}{12(1-\nu^2)}$$

* Equilibrium : Von Kármán equations

$$N_{x,x} + N_{xy,y} = 0$$

$$N_{xy,x} + M_{y,y} = 0$$

$$D \nabla^4 w - (N_x w_{,xx} + 2N_{xy} w_{,xy} + N_y w_{,yy}) = p$$

REMARK :

- * Let's introduce a "stress function" $f(x, y)$ by :

$$\begin{cases} N_x = f_{,yy} \\ N_y = f_{,xx} \\ N_{xy} = -f_{,yx} \end{cases}$$

- * and a bracket (Monge - Ampère form) :

$$[f, g] \stackrel{\text{def}}{=} f_{,xx}g_{,yy} + f_{,yy}g_{,xx} - 2f_{,xy}g_{,xy}$$

- * Then the set of von Kármán equations is changed into :

$$\nabla^4 f = -Eh[w, w]$$

$$D \nabla^4 w = [f, w] + p$$

+
B.C.

Assume for a given load p , there exists a solution (u_0, v_0, w_0) corresponding to N_{x0}, N_{y0}, \dots

* "Adjacent" equilibrium :

$\exists? (\tilde{u}, \tilde{v}, \tilde{w}) \neq 0 \text{ &}$

$u = u_0 + \tilde{u}, v = v_0 + \tilde{v}, w = w_0 + \tilde{w}$
is also a solution for the same p

Then:

$$\tilde{N}_{x,x} + \tilde{N}_{ay,y} = 0$$

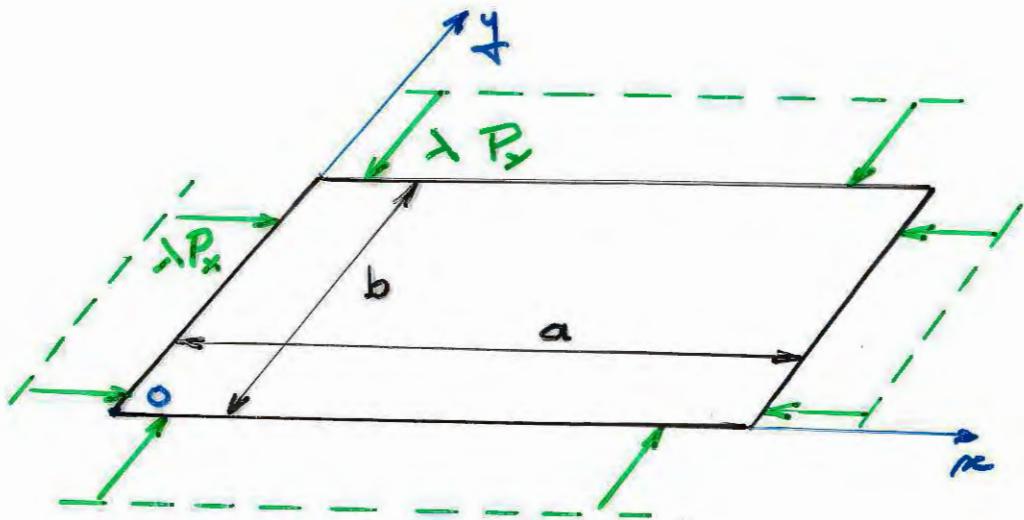
$$\tilde{N}_{ay,x} + \tilde{N}_{y,y} = 0$$

$$D \nabla^4 \tilde{w} - (N_{x0} \tilde{w}_{,xx} + 2N_{xy0} \tilde{w}_{,xy} + N_{y0} \tilde{w}_{,yy}) = 0$$

- Homogeneous

- Uncoupled

- Linear.



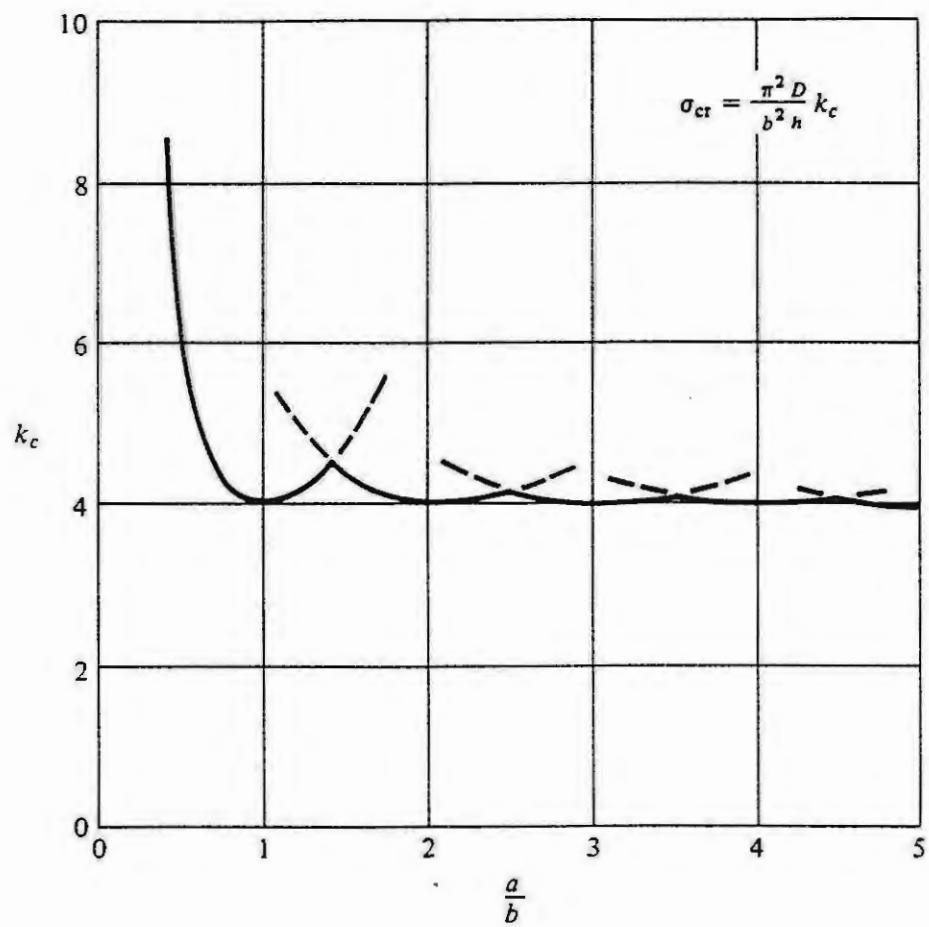
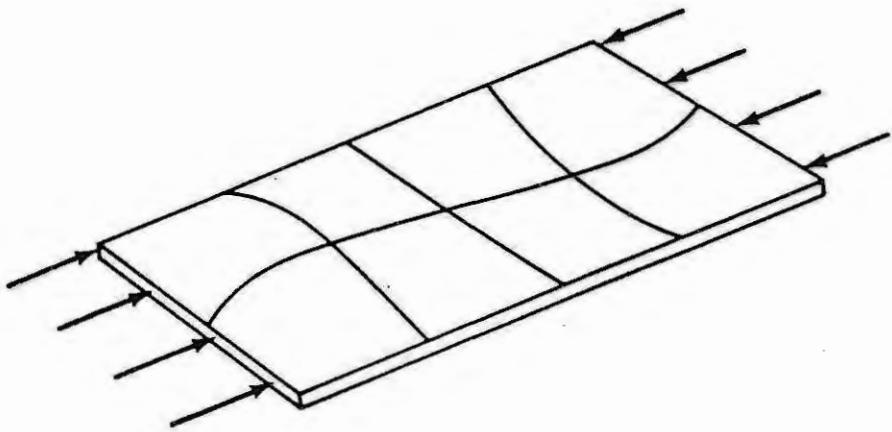
$$\left\{ \begin{array}{l} N_{x0} = -\lambda P_m; N_{y0} = -\lambda P_y; N_{xy0} = 0; \\ D \nabla^4 w + \lambda P_m w_{xx} + \lambda P_y w_{yy} = 0 \\ w = w_{xx} = 0 \text{ en } x=0 \text{ et } x=a \\ w = w_{yy} = 0 \text{ en } y=0 \text{ et } y=b \end{array} \right.$$

* $w(x, y) = \sin \frac{m\pi x}{a} \sin \frac{n\pi y}{b}$

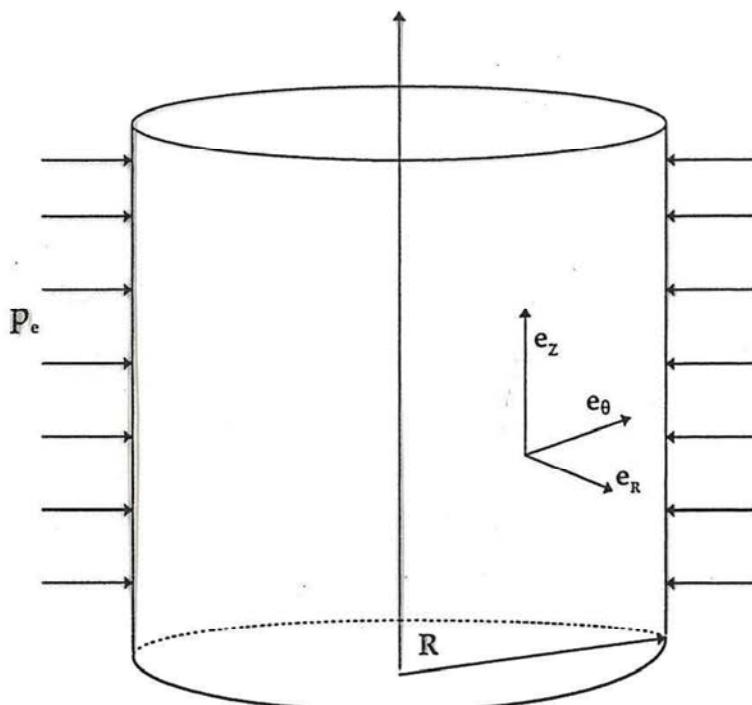
↳ $\lambda_c = h\pi^2 D$, $h = \frac{\left[\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2\right]^2}{\left(\frac{m}{a}\right)^2 P_x + \left(\frac{n}{b}\right)^2 P_y}$

* $P_y = 0 \rightarrow n = 1$

$\boxed{\lambda_c = h \frac{\pi^2 D}{b^2}, h = \left(\frac{mb}{a} + \frac{a}{mb}\right)^2 \frac{1}{P_x}}$



CYLINDRICAL SHELLS



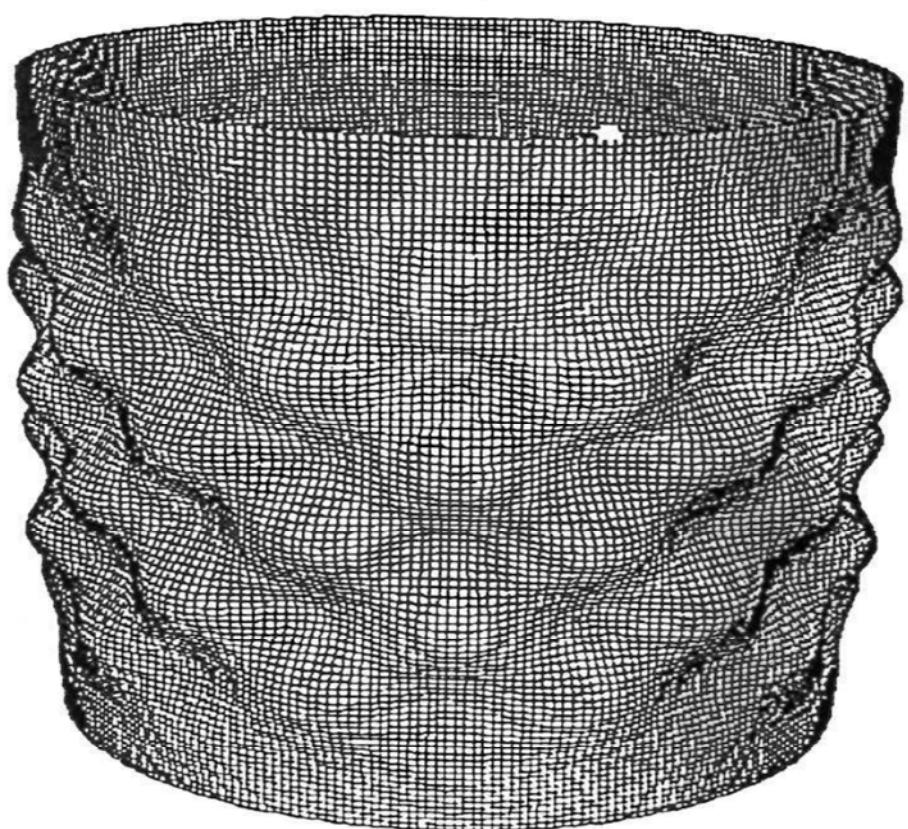
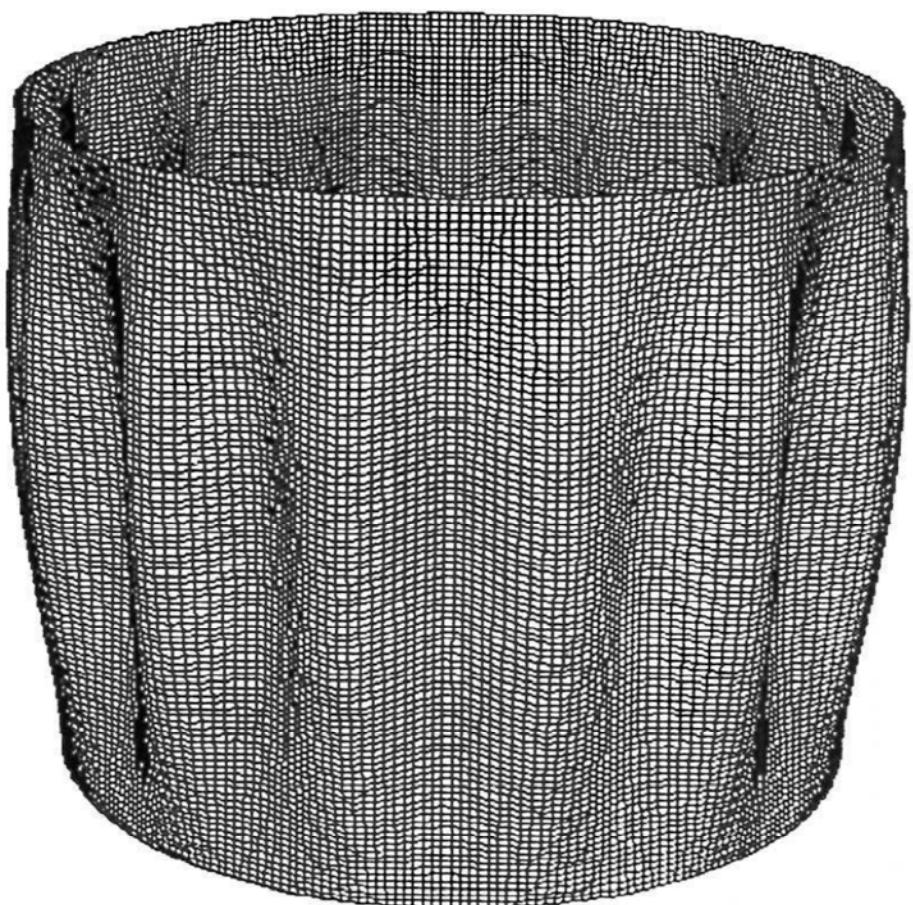
$$\left\{ \begin{array}{l} D \nabla^4 w + R f_{,zzz} - [f_{,00} w_{,zz} - 2f_{,z0} w_{,z0} + f_{,00} w_{,00}] = P \\ \nabla^4 f - \frac{Eh}{R^4} [w_{,zz}^2 - w_{,zz} w_{,00} + R w_{,00}] = 0 \end{array} \right.$$

Perturbation autour de $N_0 = -P_e R$:

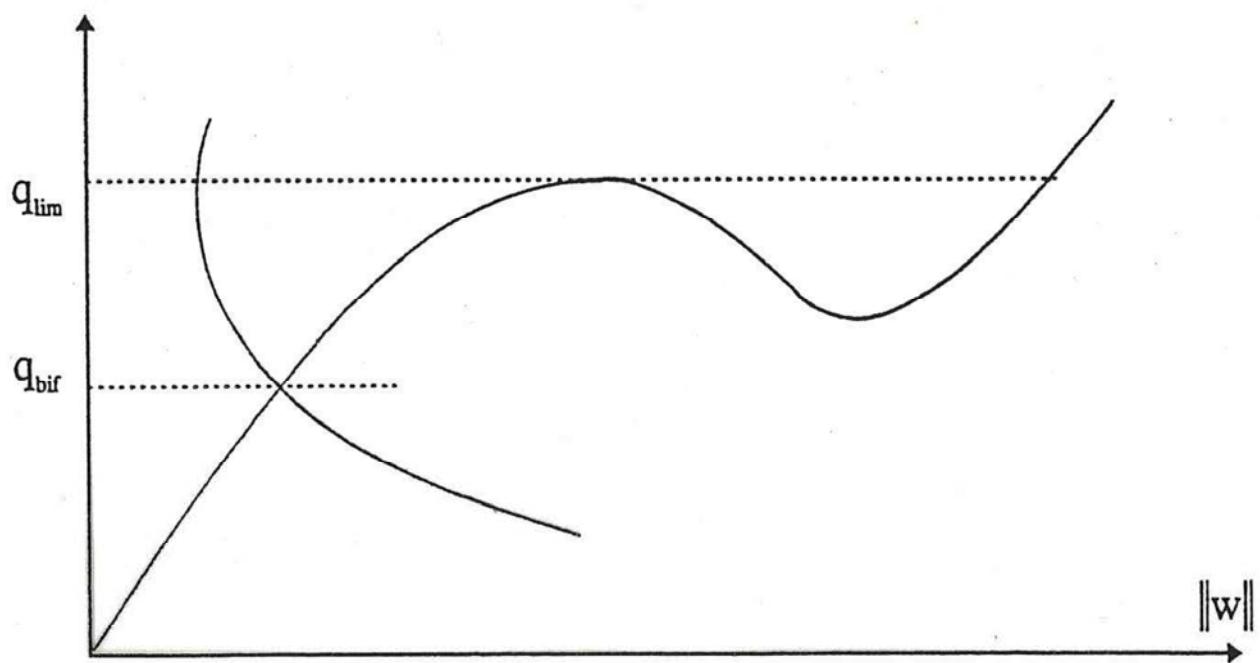
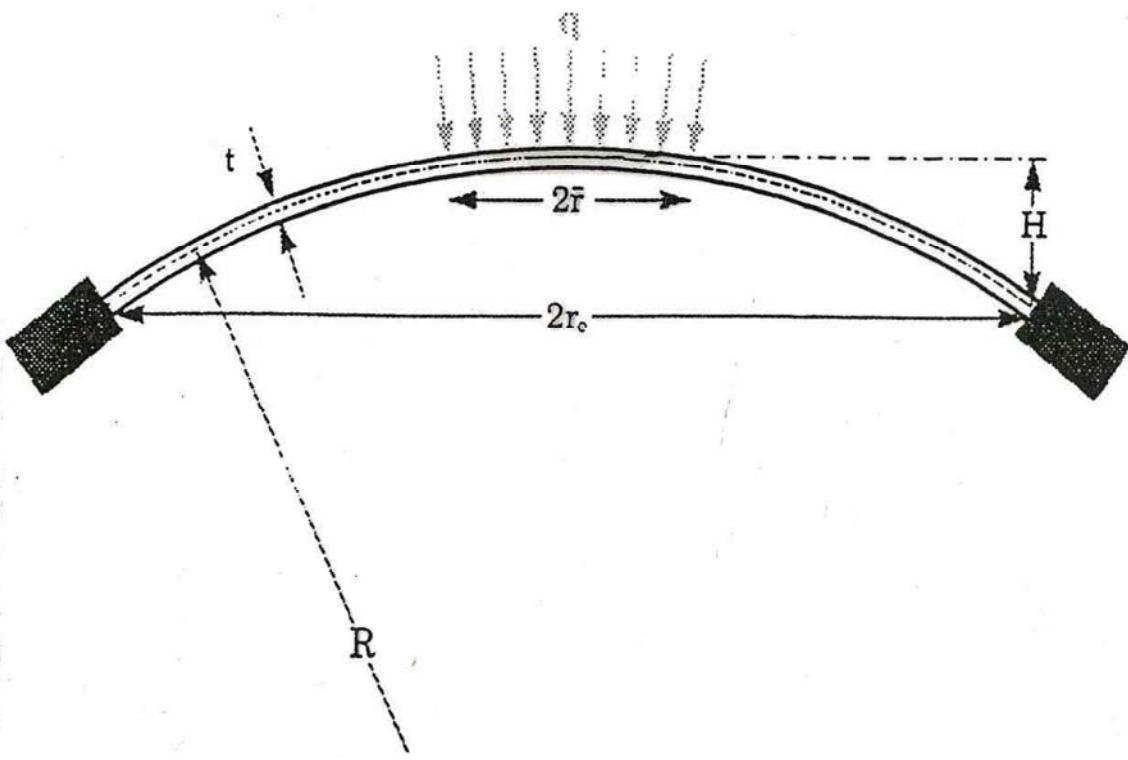
$$\left\{ \begin{array}{l} D \nabla^2 w + \frac{1-v^2}{R^2} C w_{,maz}^{(4)} + \frac{1}{R} P_e \nabla^4 w_{,00} = 0 \\ + C.L. \end{array} \right.$$

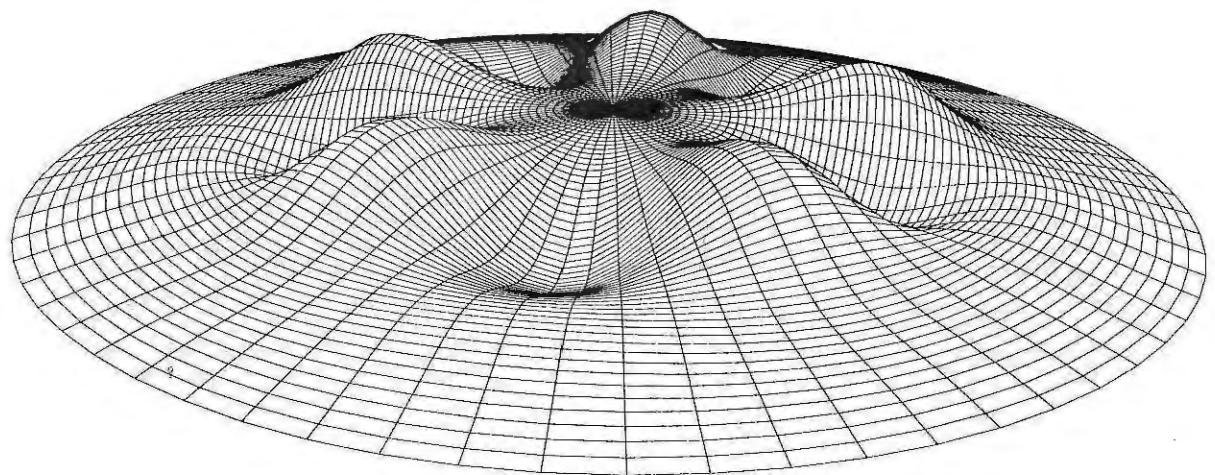
$$\hookrightarrow w = A \sin \bar{m} \varphi \cdot \sin n \theta , \quad \bar{m} = m \frac{\pi R}{L}$$

$$\hookrightarrow P_e R = \frac{(\bar{m}^2 + n^2)^2 D}{n^2 R} + \frac{\bar{m}^4}{n^2 (\bar{m}^2 + n^2)^2} (1-v^2) C$$

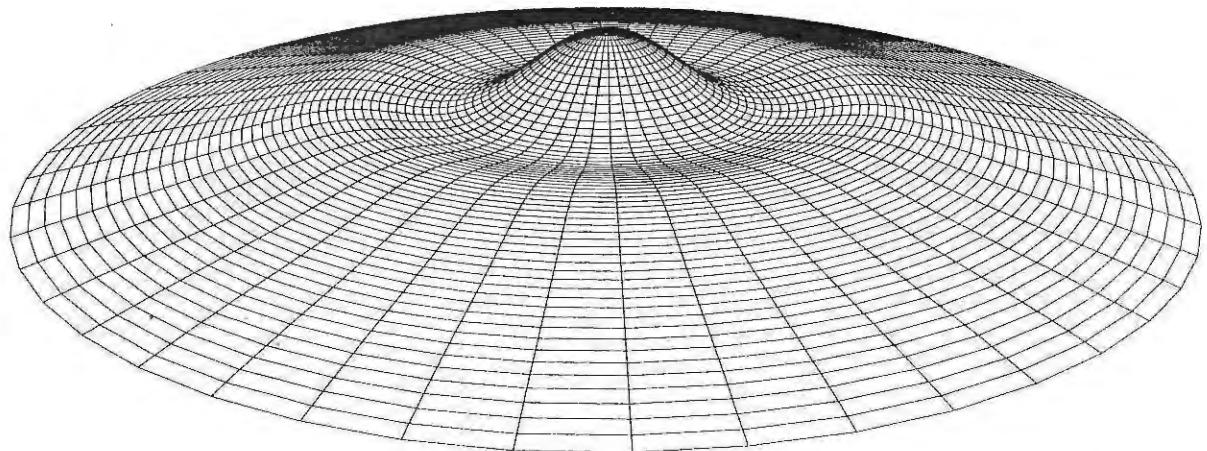


SPHERICAL CAP



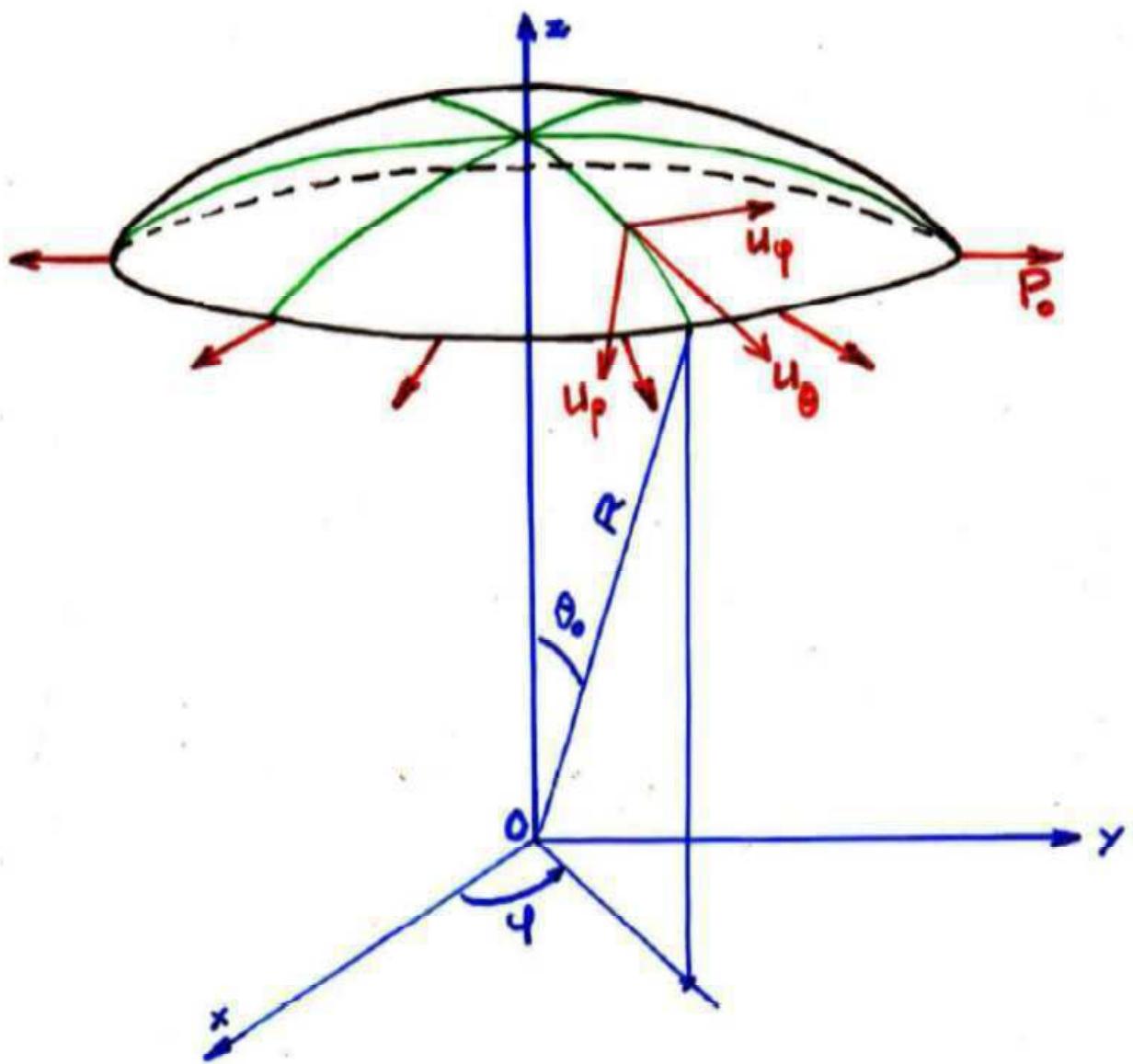


ALU - lamda = 9 - lamda barre = 8.4 - flambage en mode 5



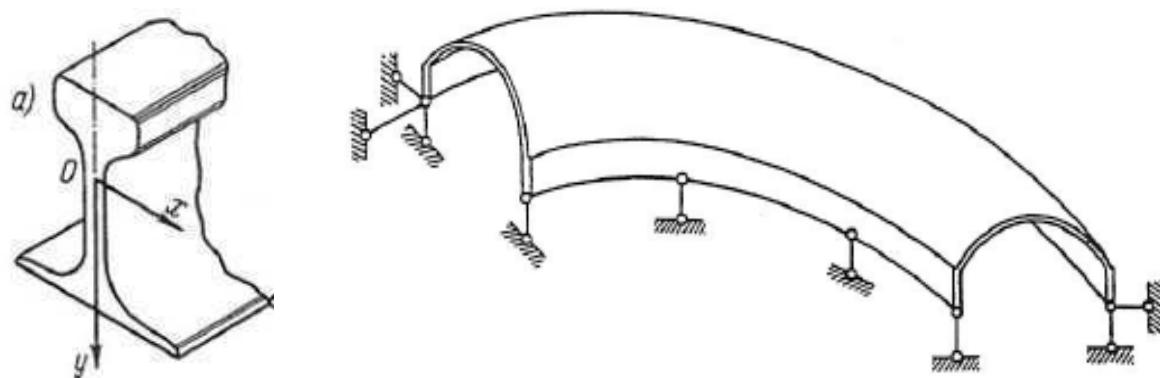
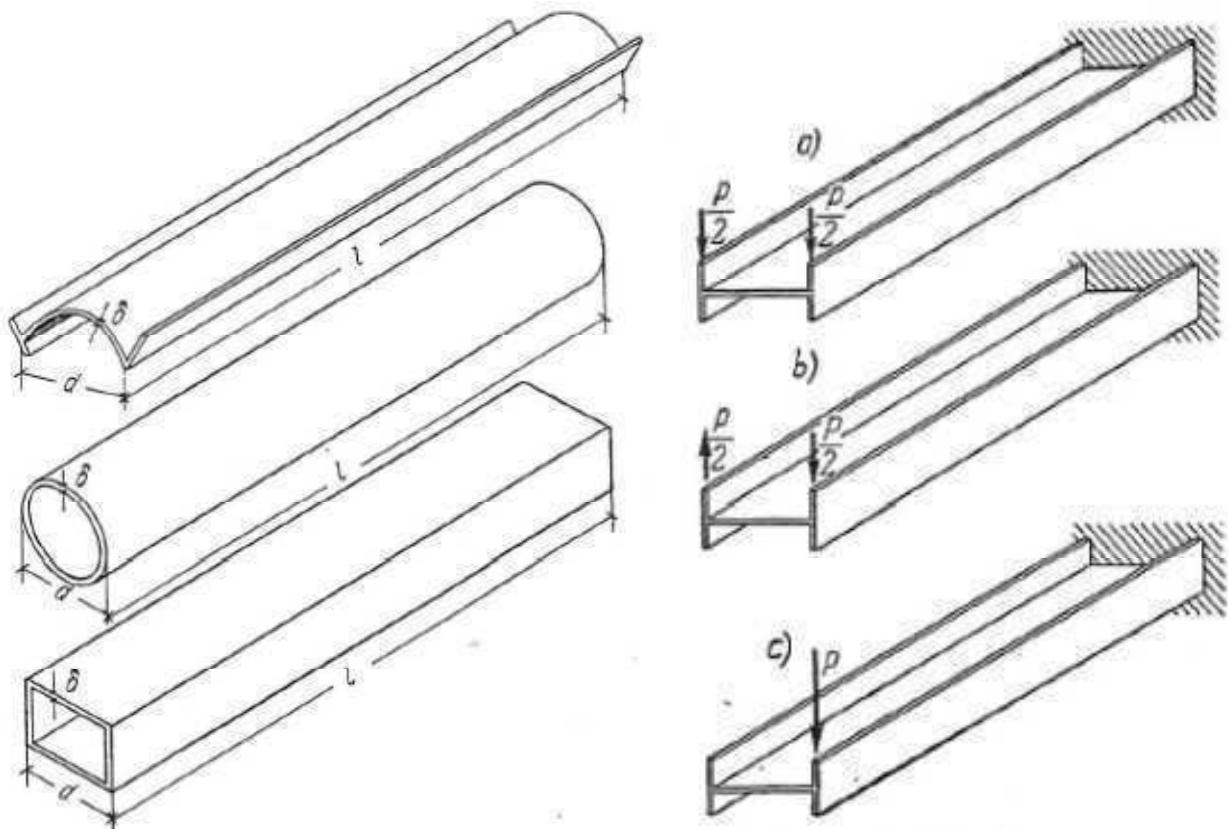
0 shows ne egadpme tifmags - 0.2 = erre esems parr - 0 = abmsi - UDA

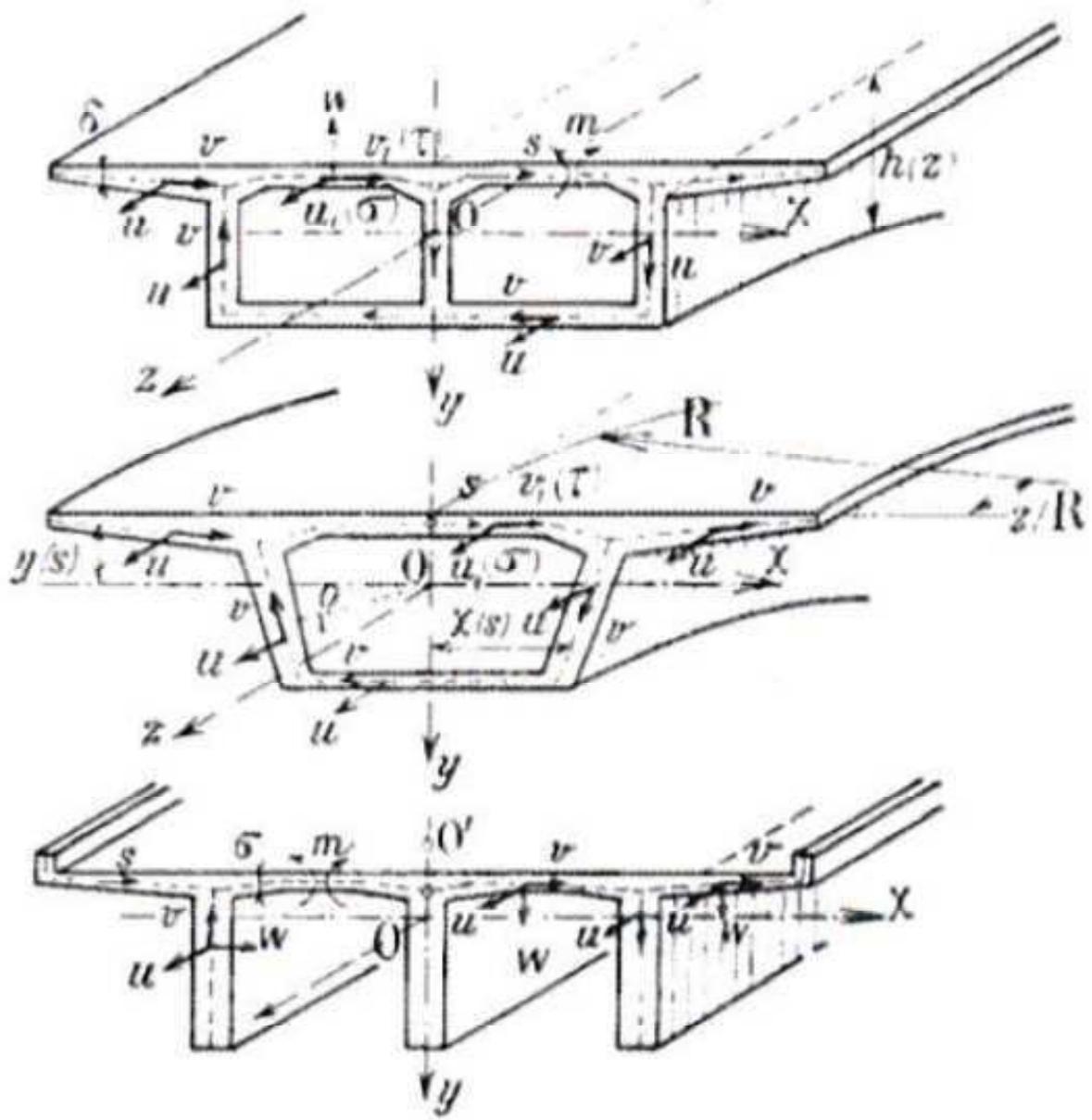
MULTI PARAMETER PROBLEMS

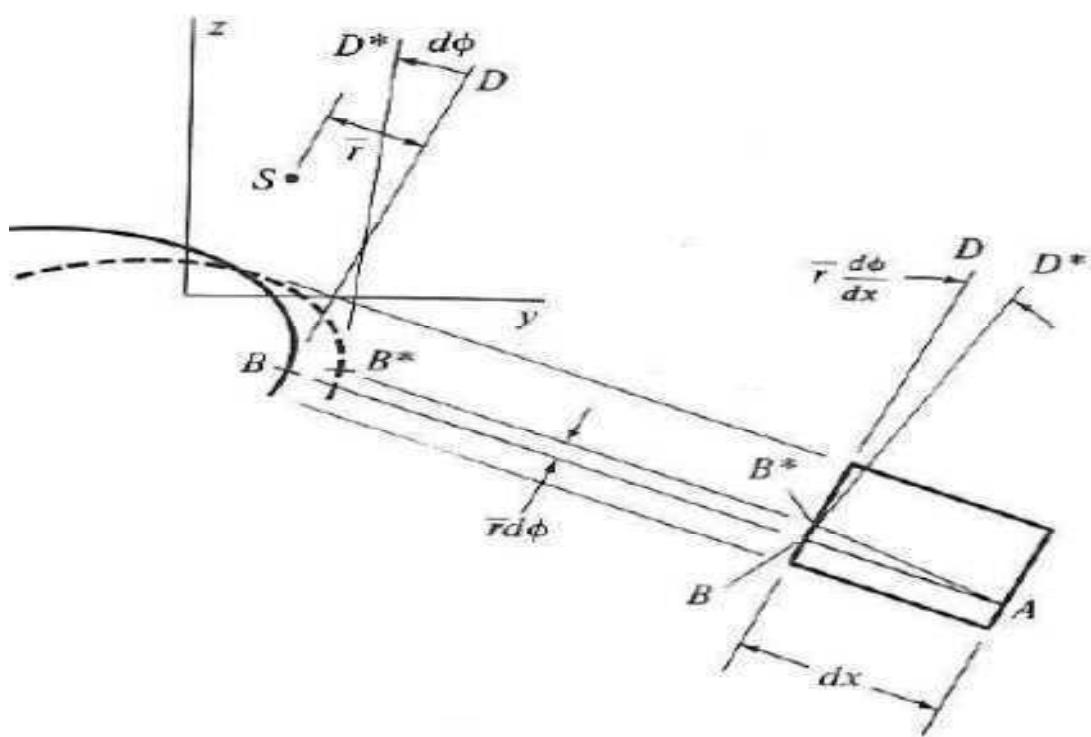
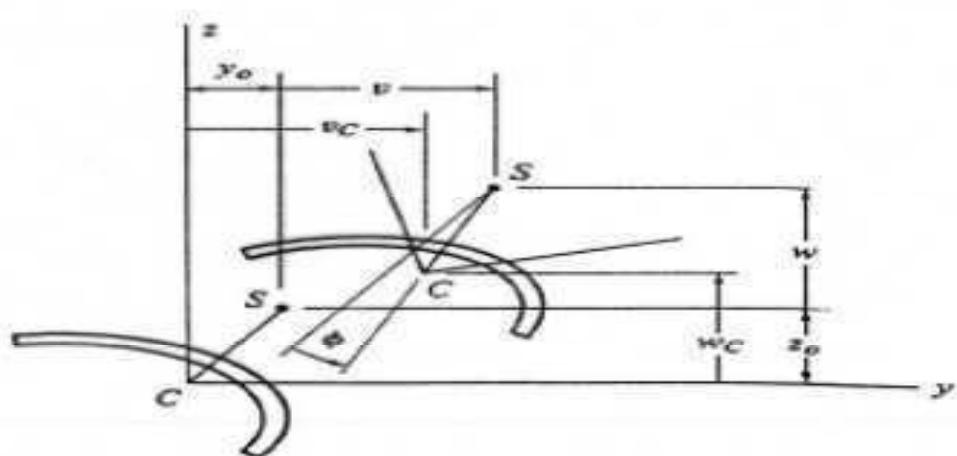
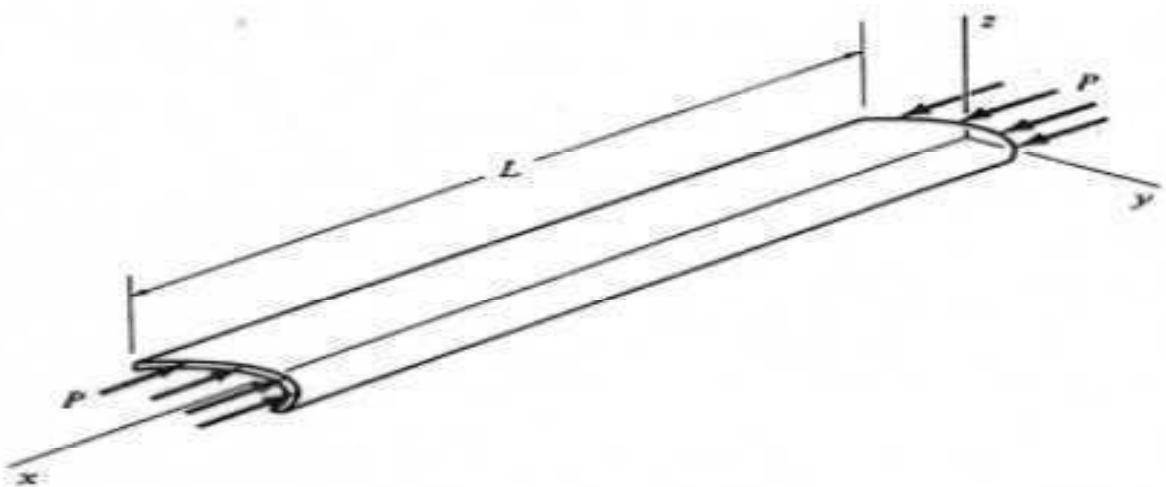


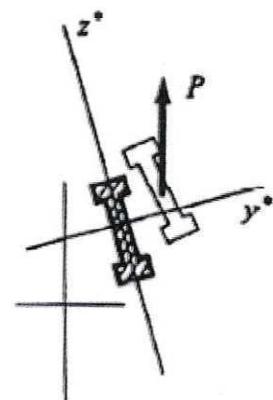
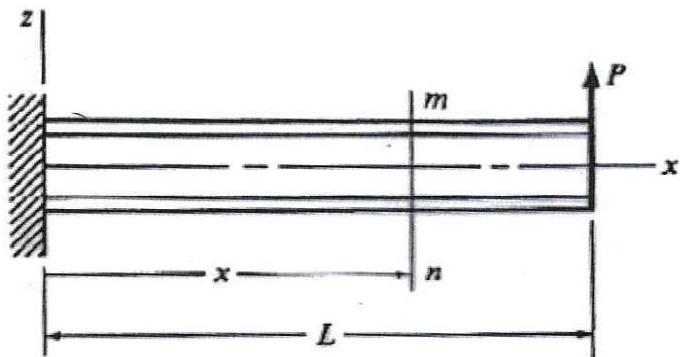
Thin-walled structures

Open or closed cross sections :









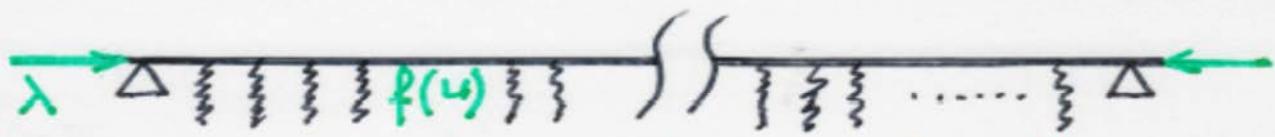
$$E C_w \phi''' - G J \phi'' - \frac{P^2}{EI_{zz}} (L - \alpha c)^2 \phi = 0$$

$$\xi = L - \alpha c, \quad k = \frac{P^2}{EI_{zz}} G J$$

→ $\frac{d^2 \phi}{d\xi^2} + k^2 \xi^2 \phi = 0$

 $k = \frac{4.013}{L^2} \text{ or } P_{cr} = 4.01 \left(EI_{zz} G J \right)^{\frac{1}{2}} \frac{L^2}{L^2}$

Very long structures



$$f(u) = k_1 u + k_3 u^3 + \dots$$

$$u''' + \lambda u'' + (\operatorname{sgn} k_3) u^3 + u = 0$$

$$u''' + \lambda u'' + u = 0$$

$$\lambda_c = 2$$

$$\varepsilon = \lambda - 2, \quad x = \varepsilon^{1/2} \propto$$

$$u = \varepsilon^{1/2} u_1 + \varepsilon u_2 + \dots$$

$$u_1 = A_1(x) e^{ix} + c.c.$$

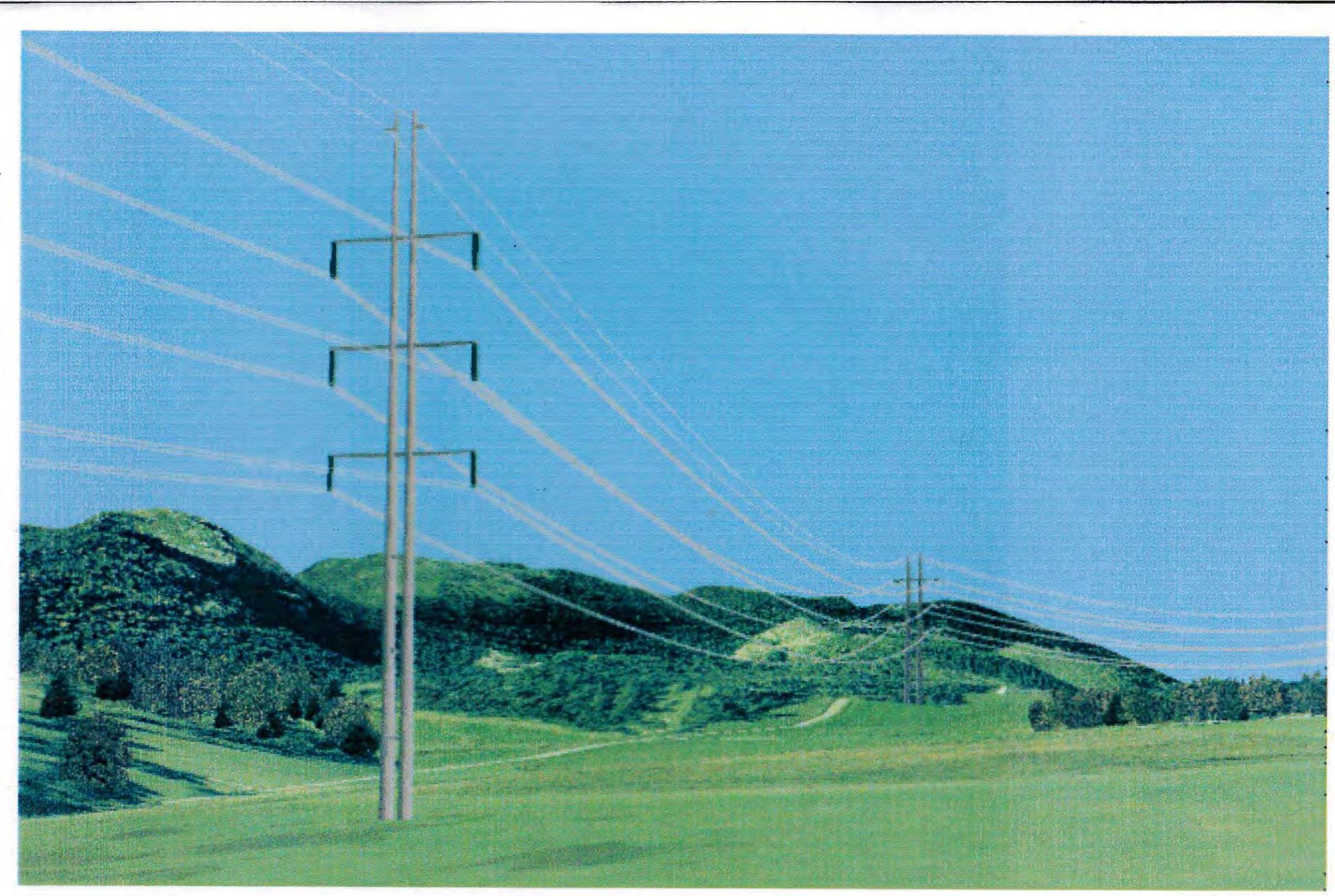
$$A_1(x) = a(x) e^{i\theta(x)}$$

$$\boxed{4A_1'' + A_1 - A_1 |A_1|^2 = 0}$$

$$a(x) = \varepsilon^{1/2} A_1(x)$$

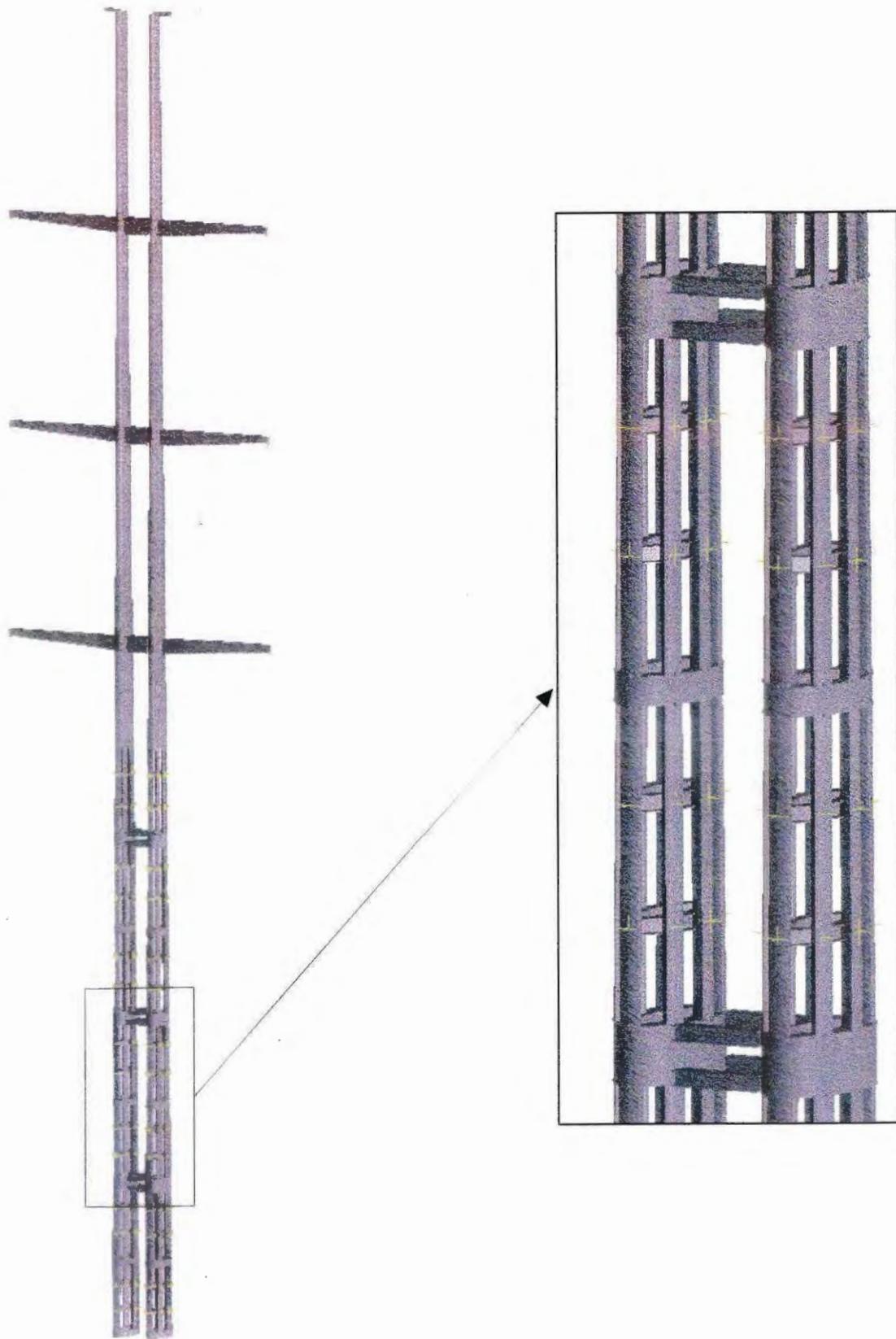
* Amplitude modulation

* Localization

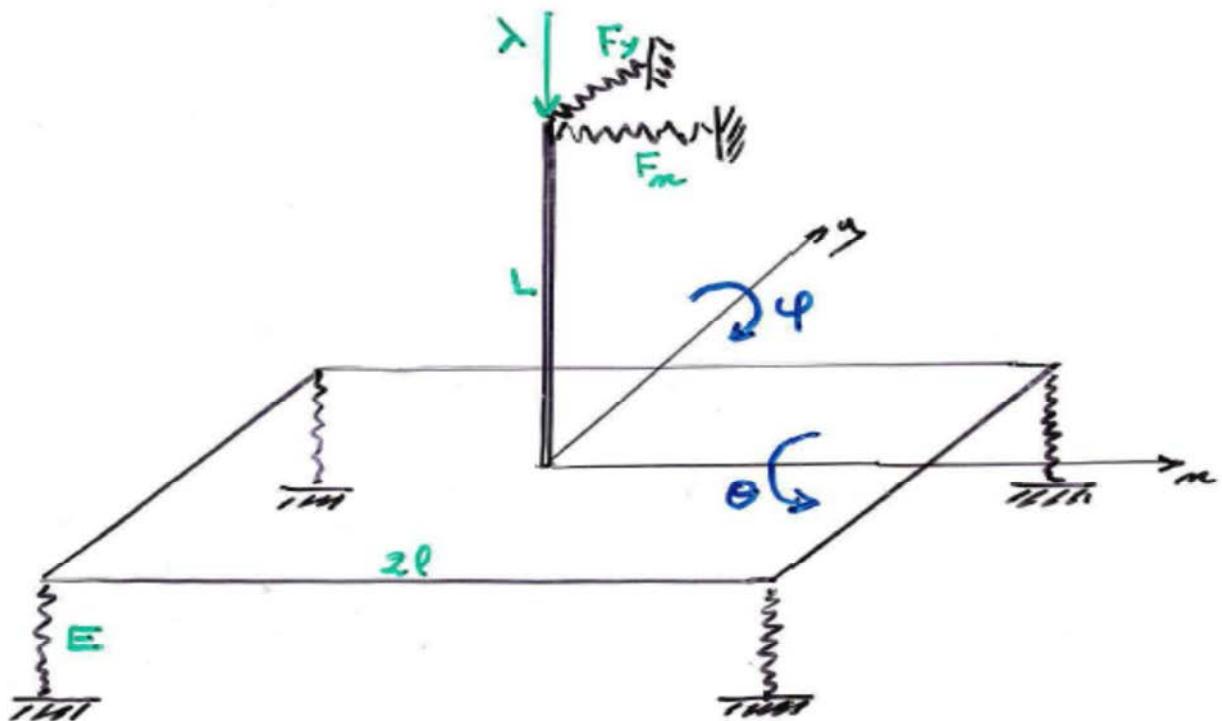




Pylônes MIMRAM

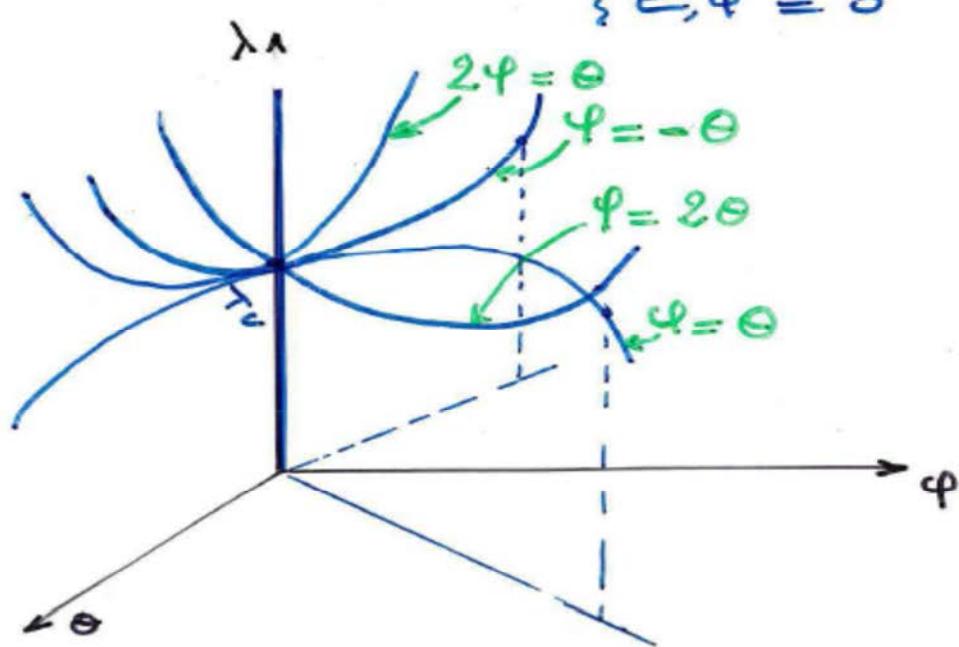


A simple model

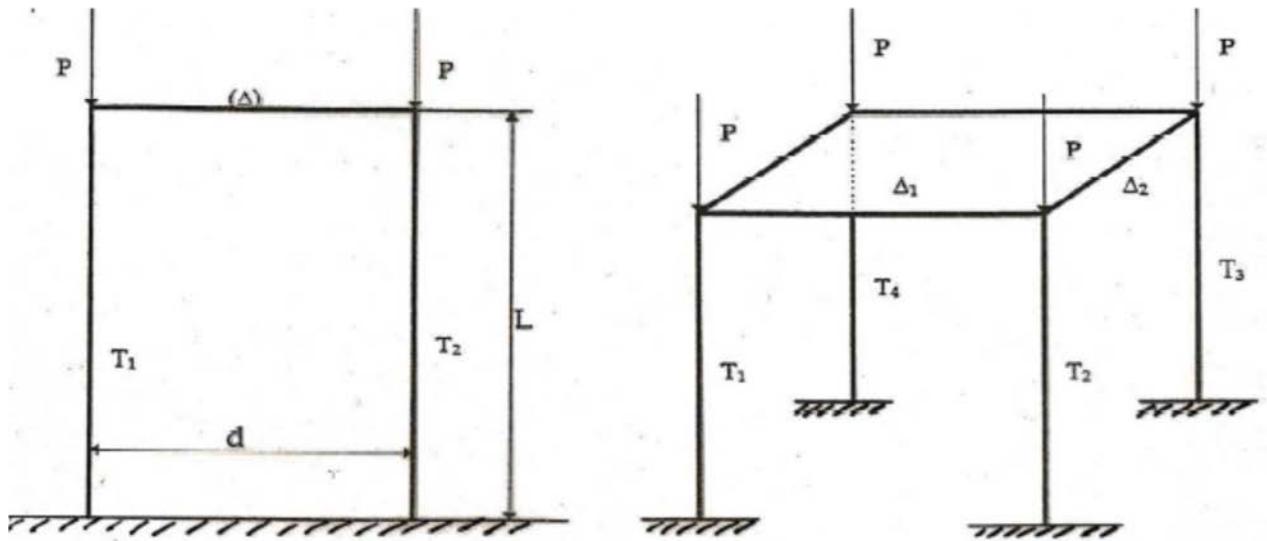


$$E(u, \theta, \varphi, \lambda)$$

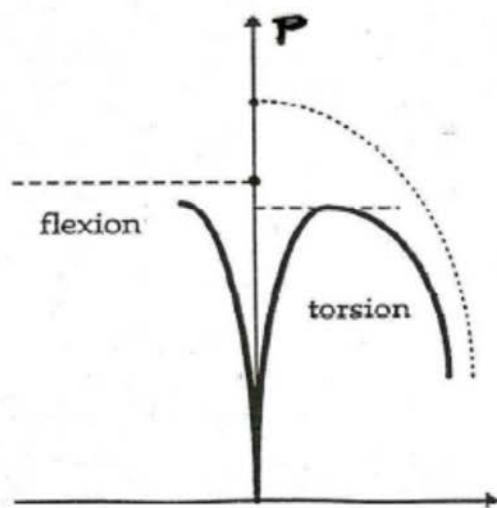
$$\Rightarrow \begin{cases} E_{,u} = 0 \\ E_{,\theta} = 0 \\ E_{,\varphi} = 0 \end{cases}$$



A slightly more complicated model

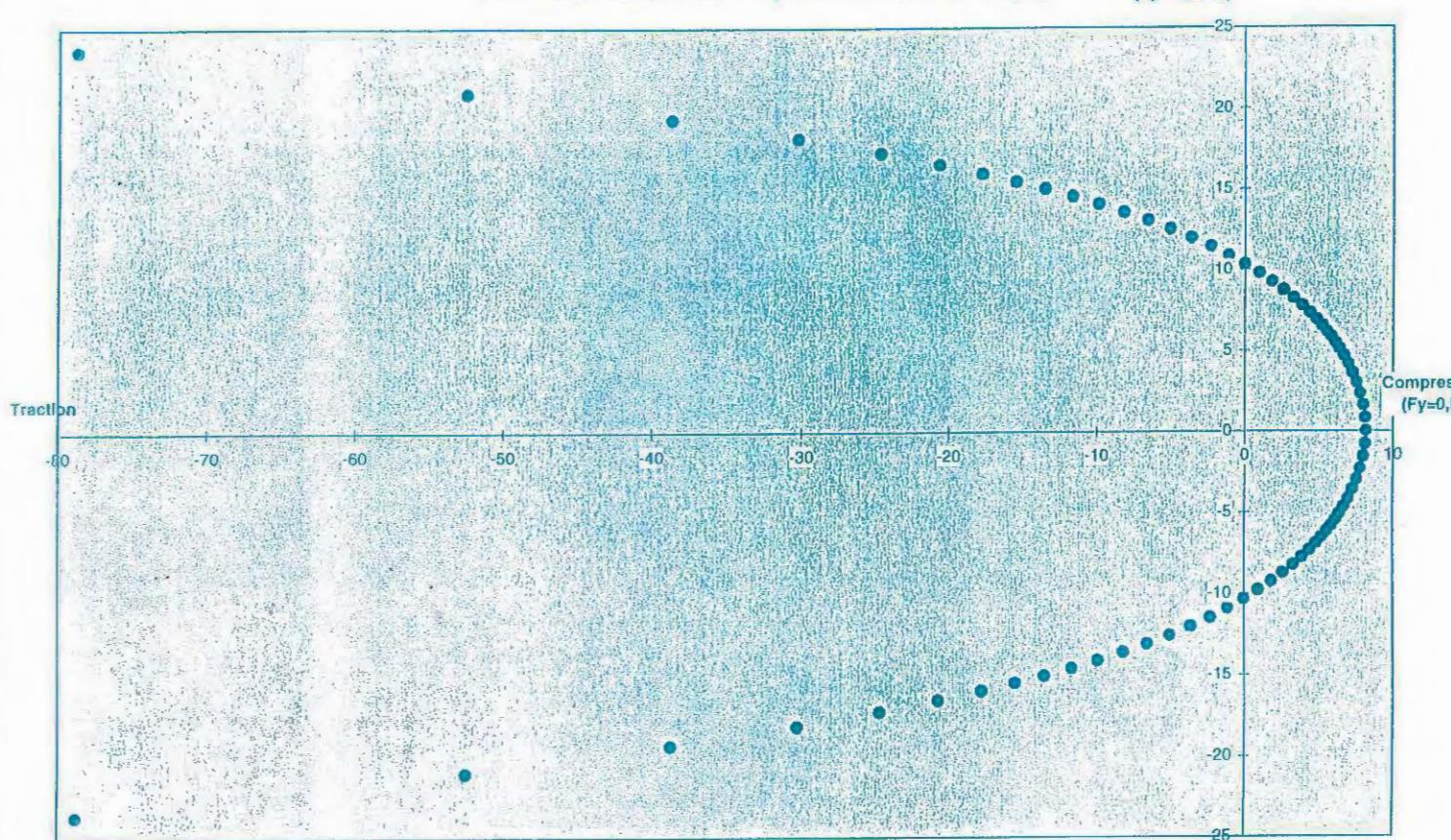


$$\left\{ \begin{array}{l} P_{cr}^{Ox} \in \left[\frac{\pi^2}{4L^2} EI_x, \frac{\pi^2}{L^2} EI_x \right] \\ P_{cr}^{Oy} \in \left[\frac{\pi^2}{4L} EI_y, \frac{\pi^2}{L} EI_y \right] \\ P_{cr}^{tors} \in \left[\min\left(\frac{\pi^2}{L^2} EI_x, \frac{\pi^2}{L^2} EI_y\right), \max\left(\frac{\pi^2}{L^2} EI_x, \frac{\pi^2}{L^2} EI_y\right) \right] \end{array} \right.$$



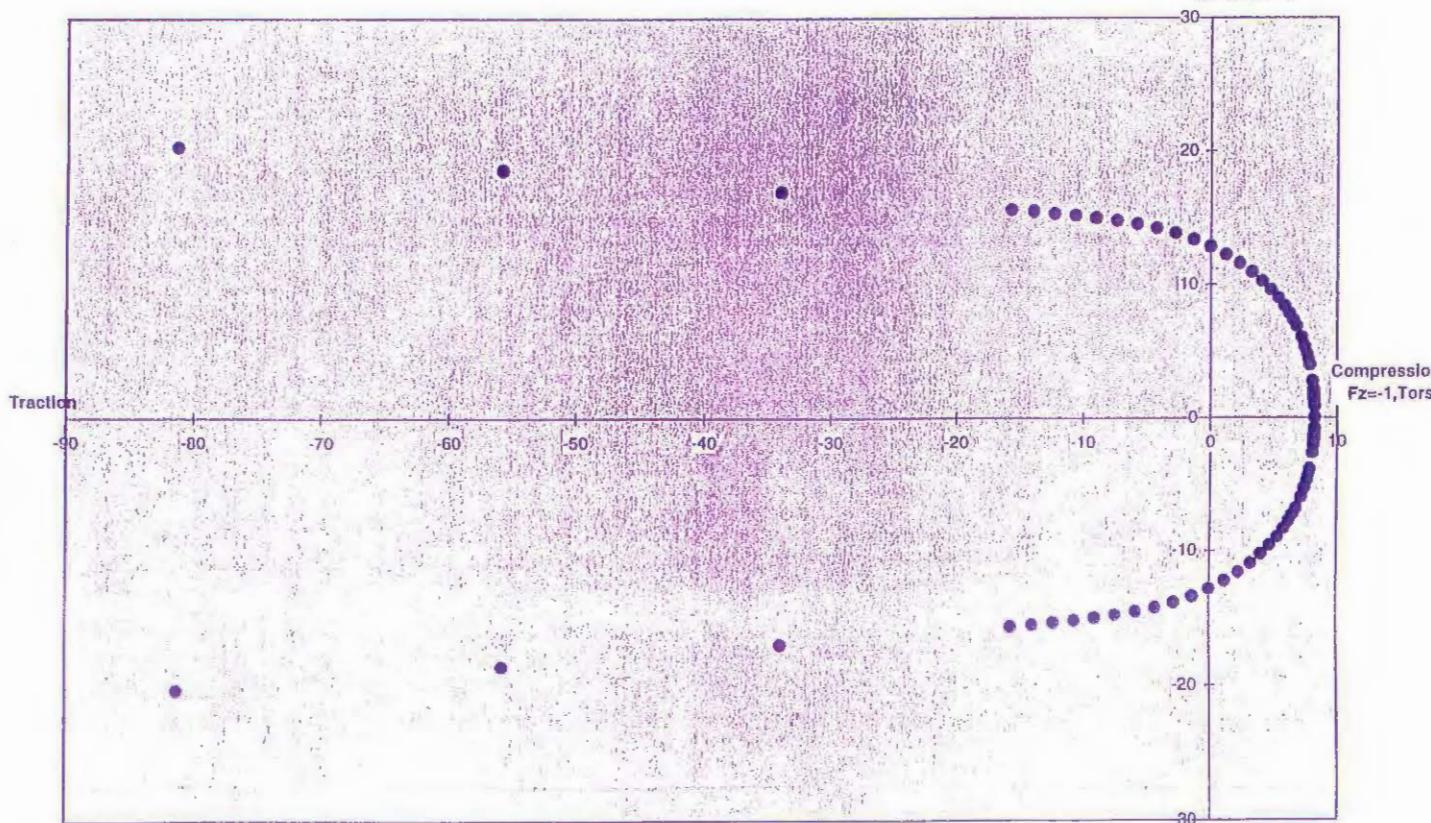
Domaine de flambement Compression/Flexion selon (Ox)

Flexion (N)
(Fy=-1,Fz=0)

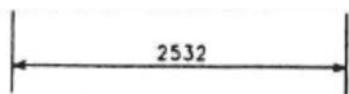
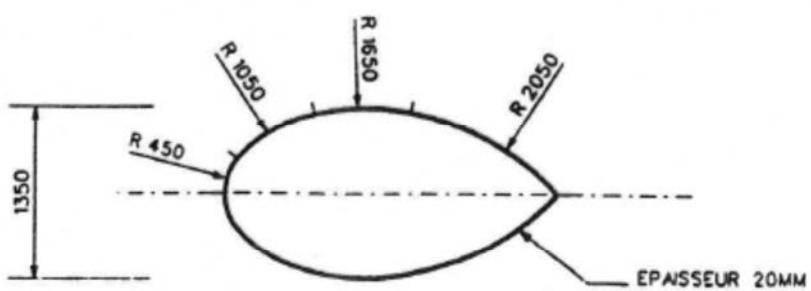


Domaine de stabilité en torsion/compression

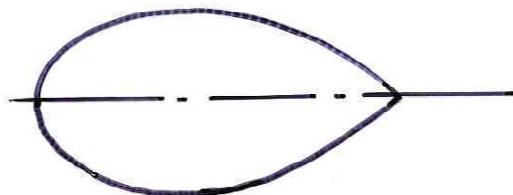
Torsion (N)
Fz=0,Tors=1



Choice of the modelling



Poutres Voiles Mince



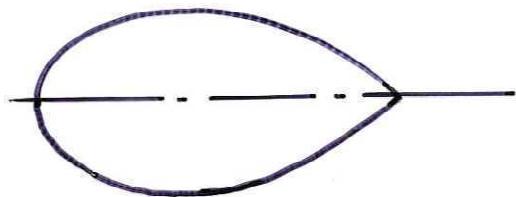
$$\left\{ \begin{array}{l} EI_y w_c^{(4)} + Pw_c'' = 0 \\ EI_3 v_c^{(4)} + Pv_c'' + Pz_c \theta_z'' = 0 \\ -M_m' + P\left(z_c^2 + \frac{I_y + I_3}{S}\right)\theta_m'' + Pz_c v_c'' = 0 \end{array} \right.$$

avec $M_m = G I_c \theta_m' + G(J-I_c)X'$

$$= GJ \theta_m' - EI_w X'''$$

+ C. L. { en déplacement de l'axe
 { en torsion
 { en ganchissement.

Poutres Voiles Mince



$$\left\{ \begin{array}{l} EI_y w_c^{(4)} + Pw_c'' = 0 \\ EI_3 v_c^{(4)} + Pv_c'' + Pz_c \theta_z'' = 0 \\ -M_m' + P\left(z_c^2 + \frac{I_y + I_3}{S}\right)\theta_m'' + Pz_c v_c'' = 0 \end{array} \right.$$

avec $M_m = G I_c \theta_m' + G(J-I_c)X'$

$$= GJ \theta_m' - EI_w X'''$$

+ C. L. { en déplacement de l'axe
 { en torsion
 { en ganchissement.

... Ou Coque Pliée

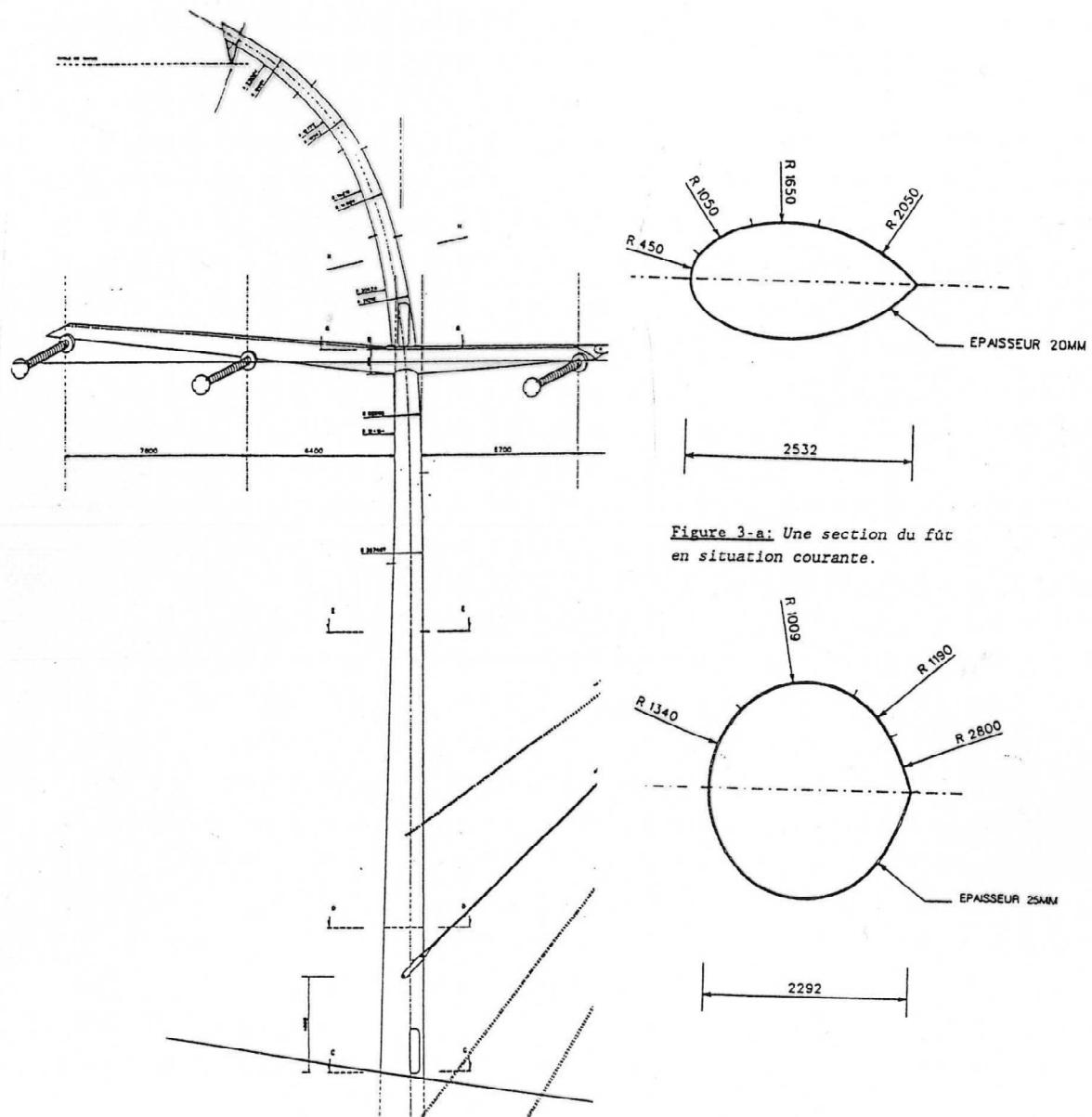
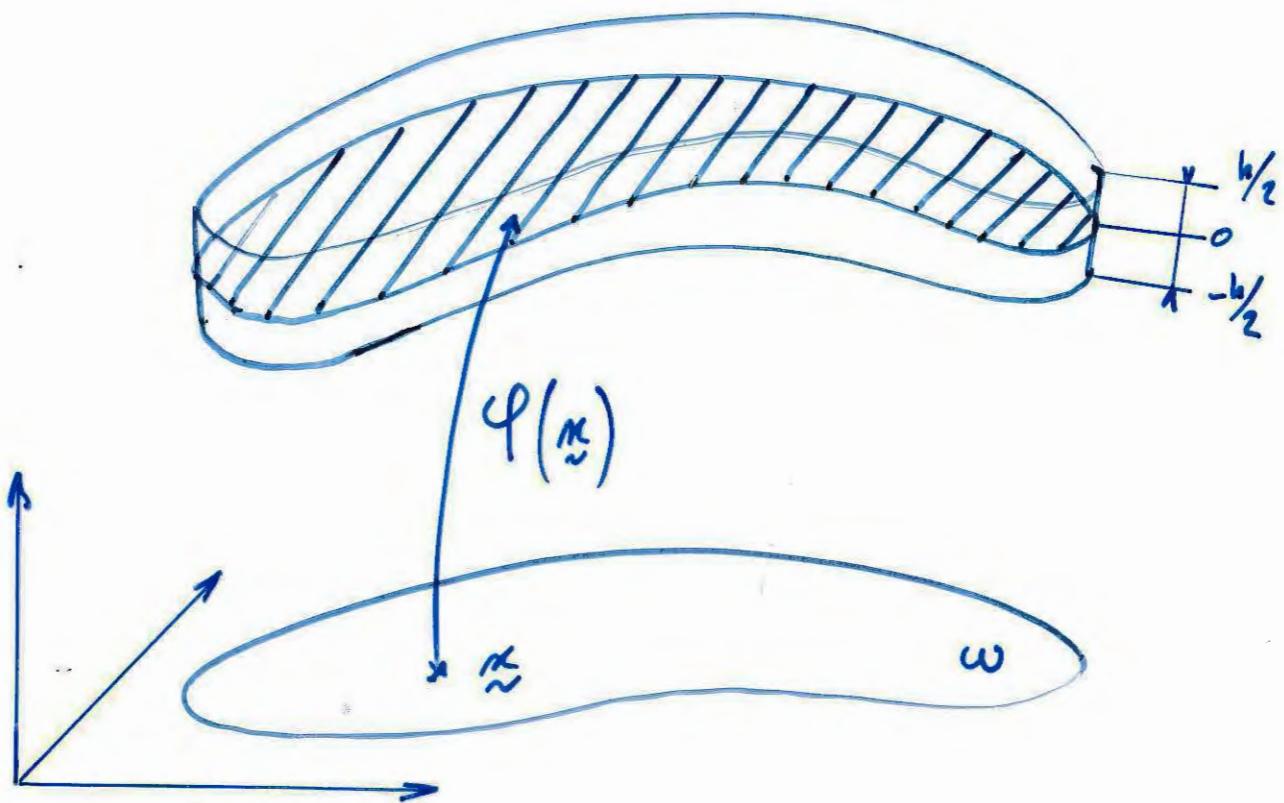


Figure 3-a: Une section du fût
en situation courante.



Classically :

$$\begin{cases} \varphi \in C^3(\omega) \\ \frac{h}{L} \ll 1, \quad \frac{h}{R_i(x)} \ll 1 \end{cases}$$

Then :

$$A(u, v) = l(v)$$



$$A(u, v) = a^m(u, v) + h^2 a^f(u, v)$$

$$A^{3D}(u,v) = l(v)$$

where:

$$A^{3D}(u,v) = \iint_{\omega}^{\frac{h}{2}} G^{\alpha\beta\rho\sigma} \xi_{\alpha\rho}(u) \xi_{\beta\sigma}(v) [1 - 2H_3 + K_3^2] \sqrt{a} dx dz$$

exactly!

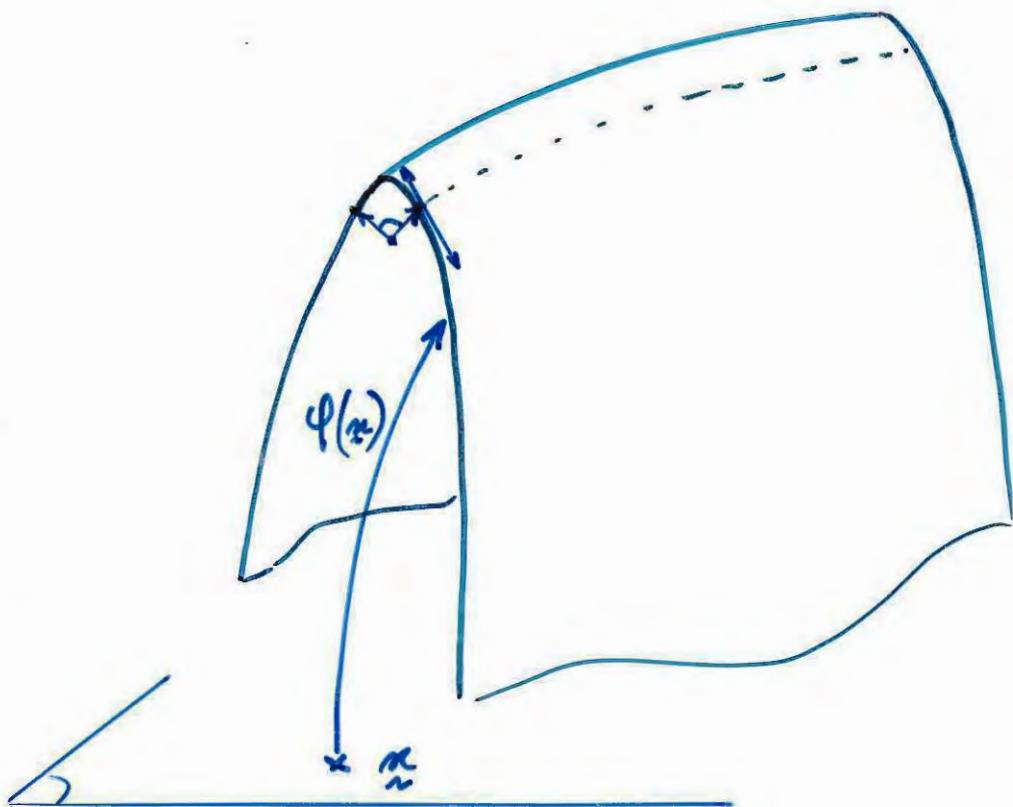
+ Integration over the cross-section

↳ $A^{2D}(u,v) = l(v)$

$A^{2D}(u,v) = A^m(u,v) + A^{mf}(u,v) + A^f(u,v)$

- * Coupling bending / membrane.
- * Same limit as "regular" models as $h \rightarrow 0$
- * Limit to a folded shell.

1st Step:



$$\varphi \in W^{2,\infty}(\omega)$$

2nd step:

Assumption of very strong curvature

$$\exists \delta > 0, \min_{x \in \bar{\omega}} R_i(x) \geq \frac{h}{2} + \delta$$

(Note the difference with classical thin shells assumption).